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ON ITERATE MINIMAL STRUCTURES AND *M*-ITERATE CONTINUOUS FUNCTIONS

ABSTRACT. We introduce the notion of mIT-structures determined by operators mInt and mCl on an *m*-space (X, m_X) . By using mIT-structures, we introduce and investigate a function $f : (X, mIT) \rightarrow (Y, m_Y)$ called MIT-continuous. As special cases of MIT-continuity, we obtain *M*-semicontinuity [21] and *M*-precontinuity [23].

KEY WORDS: *m*-structure, *M*-continuous, *m*-semiopen, *m*-preopen, *mIT*-structure, *MIT*-continuous.

AMS Mathematics Subject Classification: 54C08.

1. Introduction

Semi-open sets, preopen sets, α -open sets, β -open sets and *b*-open sets play an important role in the researches of generalizations of continuity in topological spaces. By using these sets, several authors introduced and studied various types of non-continuous functions. Certain of these non-continuous functions have properties similar to those of continuous functions and they hold, in many part, parallel to the theory of continuous functions.

In [26] and [27], the present authors introduced and studied the notions of minimal structures, *m*-spaces, *m*-continuity and *M*-continuity. Quite recently, in [19], [20] and [22], Min and Kim introduced the notions of *m*-semiopen sets, *m*-preopen sets and αm -open sets which generalize the notion of *m*-open sets and also *M*-semicontinuity, *M*-precontinuity and αM -continuity which generalize the notion of *M*-continuity. Rosas et al. [30] also introduced the notions of *m*-semiopen sets and *m*-preopen sets. The notion of βm -open sets is introduced by Boonpok [5].

The notions of *m*-semiopen sets, *m*-preopen sets, αm -open sets and βm -open sets are defined by using the *m*-interior mInt and the *m*-closure mCl on an *m*-space (X, m_X) . The each family of *m*-semiopen sets, *m*-preopen sets, αm -open sets or βm -open sets becomes an *m*-structure with property \mathcal{B} , that is, it is closed under arbitrary union. The purpose of the present

paper is to obtain the unified theory of M-semicontinuity, M-precontinuity, αM -continuity, βM -continuity and M-b-continuity.

2. Preliminaries

Let (X, τ) be a topological space and A a subset of X. The closure of A and the interior of A are denoted by Cl(A) and Int(A), respectively. We recall some generalized open sets in topological spaces.

Definition 1. Let (X, τ) be a topological space. A subset A of X is said to be

(a) α -open [24] if $A \subset Int(Cl(Int(A)))$,

(b) semi-open [11] if $A \subset Cl(Int(A))$,

(c) preopen [16] if $A \subset Int(Cl(A))$,

(d) b-open [4] or γ -open [9] if $A \subset Int(Cl(A)) \cup Cl(Int(A))$,

(e) β -open [1] or semi-preopen [3] if $A \subset Cl(Int(Cl(A)))$.

The family of all α -open (resp. semi-open, preopen, b-open, β -open) sets in (X, τ) is denoted by $\alpha(X)$ (resp. SO(X), PO(X), BO(X), $\beta(X)$).

Definition 2. Let (X, τ) be a topological space. A subset A of X is said to be α -closed [18] (resp. semi-closed [6], preclosed [16], b-closed [4], β -closed [1]) if the complement of A is α -open (resp. semi-open, preopen, b-open, β -open).

Definition 3. Let (X, τ) be a topological space and A a subset of X. The intersection of all α -closed (resp. semi-closed, preclosed, b-closed, β -closed) sets of X containing A is called the α -closure [18] (resp. semi-closure [6], preclosure [10], b-closure [4], β -closure [2]) of A and is denoted by $\alpha Cl(A)$ (resp. sCl(A), pCl(A), bCl(A), $\beta Cl(A)$).

Definition 4. Let (X, τ) be a topological space and A a subset of X. The union of all α -open (resp. semi-open, preopen, b-open, β -open) sets of X contained in A is called the α -interior [18] (resp. semi-interior [6], preinterior [10], b-interior [4], β -interior [2]) of A and is denoted by α Int(A)(resp. sInt(A), pInt(A), bInt(A), β Int(A)).

Definition 5. A function $f: (X, \tau) \to (Y, \sigma)$ is said to be irresolute [7] (resp. preirresolute [29] or *M*-preirresolute [17], α -irresolute [13] or strongly feebly continuous [12], γ -irresolute (= b-irresolute) [8], β -irresolute [14]) at $x \in X$ if for each semi-open (resp. preopen, α -open, γ -open, β -open) set *V* containing f(x), there exists a semi-open (resp. preopen, α -open, γ -open, β -open) set *U* of *X* containing *x* such that $f(U) \subset V$. The function *f* is said to be irresolute (resp. preirresolute, α -irresolute, γ -irresolute, β -irresolute) if it has this property at each point $x \in X$.

3. Minimal structures and *M*-continuity

Definition 6. Let X be a nonempty set and $\mathcal{P}(X)$ the power set of X. A subfamily m_X of $\mathcal{P}(X)$ is called a minimal structure (briefly m-structure) on X [26], [27] if $\emptyset \in m_X$ and $X \in m_X$.

By (X, m_X) , we denote a nonempty set X with an *m*-structure m_X on X and call it an *m*-space. Each member of m_X is said to be m_X -open (briefly *m*-open) and the complement of an m_X -open set is said to be m_X -closed (briefly *m*-closed).

Remark 1. Let (X, τ) be a topological space. The families τ , $\alpha(X)$, SO(X), PO(X), BO(X) and $\beta(X)$ are all minimal structures on X.

Definition 7. Let X be a nonempty set and m_X an m-structure on X. For a subset A of X, the m_X -closure of A and the m_X -interior of A are defined in [15] as follows:

(a) $\mathrm{mCl}(A) = \cap \{F : A \subset F, X \setminus F \in m_X\},\$

(b) $\operatorname{mInt}(A) = \bigcup \{ U : U \subset A, U \in m_X \}.$

Remark 2. Let (X, τ) be a topological space and A a subset of X. If $m_X = \tau$ (resp. SO(X), PO(X), $\alpha(X)$, BO(X), $\beta(X)$), then we have

(a) $\mathrm{mCl}(A) = \mathrm{Cl}(A)$ (resp. $\mathrm{sCl}(A)$, $\mathrm{pCl}(A)$, $\alpha \mathrm{Cl}(A)$, $\mathrm{bCl}(A)$, $_{\beta}\mathrm{Cl}(A)$),

(b) $\operatorname{mInt}(A) = \operatorname{Int}(A)$ (resp. $\operatorname{sInt}(A)$, $\operatorname{pInt}(A)$, $\alpha \operatorname{Int}(A)$, $\beta \operatorname{Int}(A)$).

Lemma 1 (Maki et al. [15]). Let X be a nonempty set and m_X a minimal structure on X. For subsets A and B of X, the following properties hold:

(a) $\operatorname{mCl}(X \setminus A) = X \setminus \operatorname{mInt}(A)$ and $\operatorname{mInt}(X \setminus A) = X \setminus \operatorname{mCl}(A)$,

(b) If $(X \setminus A) \in m_X$, then $\mathrm{mCl}(A) = A$ and if $A \in m_X$, then $\mathrm{mInt}(A) = A$,

(c) $\mathrm{mCl}(\emptyset) = \emptyset$, $\mathrm{mCl}(X) = X$, $\mathrm{mInt}(\emptyset) = \emptyset$ and $\mathrm{mInt}(X) = X$,

(d) If $A \subset B$, then $\operatorname{mCl}(A) \subset \operatorname{mCl}(B)$ and $\operatorname{mInt}(A) \subset \operatorname{mInt}(B)$,

(e) $A \subset \mathrm{mCl}(A)$ and $\mathrm{mInt}(A) \subset A$,

(f) mCl(mCl(A)) = mCl(A) and mInt(mInt(A)) = mInt(A).

Lemma 2 (Popa and Noiri [26]). Let (X, m_X) be an *m*-space and *A* a subset of *X*. Then $x \in \mathrm{mCl}(A)$ if and only if $U \cap A \neq \emptyset$ for each $U \in m_X$ containing *x*.

Definition 8. A minimal structure m_X on a nonempty set X is said to have property \mathcal{B} [15] if the union of any family of subsets belonging to m_X belongs to m_X .

Remark 3. If (X, τ) is a topological space, then the *m*-structures SO(X), PO(X), $\alpha(X)$, BO(X) and $\beta(X)$ have property \mathcal{B} .

Lemma 3 (Popa and Noiri [28]). Let X be a nonempty set and m_X an *m*-structure on X satisfying property \mathcal{B} . For a subset A of X, the following properties hold:

(a) $A \in m_X$ if and only if $\operatorname{mInt}(A) = A$,

(b) A is m_X -closed if and only if mCl(A) = A,

(c) $\operatorname{mInt}(A) \in m_X$ and $\operatorname{mCl}(A)$ is m_X -closed.

Definition 9. A function $f : (X, m_X) \to (Y, m_Y)$ is said to be *M*-continuous at $x \in X$ [26] if for each m_Y -open set *V* containing f(x), there exists $U \in m_X$ containing x such that $f(U) \subset V$. The function f is *M*-continuous if it has this property at each $x \in X$.

Theorem 1 (Popa and Noiri [26]). For a function $f : (X, m_X) \rightarrow (Y, m_Y)$, the following properties are equivalent:

(a) f is M-continuous;

(b) $f^{-1}(V) = \operatorname{mInt}(f^{-1}(V))$ for every m-open set V of Y;

(c) $f^{-1}(F) = \mathrm{mCl}(f^{-1}(F))$ for every *m*-closed set *F* of *Y*;

(d) $\mathrm{mCl}(f^{-1}(B)) \subset f^{-1}(\mathrm{mCl}(B))$ for every subset B of Y;

(e) $f(\mathrm{mCl}(A)) \subset \mathrm{mCl}(f(A))$ for every subset A of X;

(f) $f^{-1}(\operatorname{mInt}(B)) \subset \operatorname{mInt}(f^{-1}(B))$ for every subset B of Y.

Corollary 1 (Popa and Noiri [26]). For a function $f : (X, m_X) \to (Y, m_Y)$, where m_X has property \mathcal{B} , the following properties are equivalent:

(a) f is M-continuous;

(b) $f^{-1}(V)$ is m-open in X for every m-open set V of Y;

(c) $f^{-1}(F)$ is m-closed in X for every m-closed set F of Y.

For a function $f: (X, m_X) \to (Y, m_Y)$, we define $D_M(f)$ as follows:

 $D_M(f) = \{x \in X : f \text{ is not } M \text{-continuous at } x\}.$

Theorem 2 (Noiri and Popa [25]). For a function $f : (X, m_X) \rightarrow (Y, m_Y)$, the following properties hold:

$$D_M(f) = \bigcup_{G \in m_Y} \{ f^{-1}(G) - \operatorname{mInt}(f^{-1}(G)) \}$$

= $\bigcup_{B \in \mathcal{P}(Y)} \{ f^{-1}(\operatorname{mInt}(B)) - \operatorname{mInt}(f^{-1}(B)) \}$
= $\bigcup_{B \in \mathcal{P}(Y)} \{ \operatorname{mCl}(f^{-1}(B)) - f^{-1}(\operatorname{mCl}(B)) \}$
= $\bigcup_{A \in \mathcal{P}(X)} \{ \operatorname{mCl}(A) - f^{-1}(\operatorname{mCl}(f(A))) \}$
= $\bigcup_{F \in \mathcal{F}} \{ \operatorname{mCl}(f^{-1}(F)) - f^{-1}(F) \},$

where \mathcal{F} is the family of m-closed sets of (Y, m_Y) .

4. *m*-Iterate structures and *M*-iterate continuity

Definition 10. Let (X, m_X) be an *m*-space. A subset A of X is said to be

(a) αm -open [20] if $A \subset mInt(mCl(mInt(A)))$,

b) m-semiopen [19] if $A \subset \mathrm{mCl}(\mathrm{mInt}(A))$,

(c) *m*-preopen [22] if $A \subset mInt(mCl(A))$,

(d) βm -open [5] if $A \subset \mathrm{mCl}(\mathrm{mInt}(\mathrm{mCl}(A)))$,

(e) m-b-open if $A \subset mInt(mCl(A)) \cup mCl(mInt(A))$.

The family of all αm -open (resp. *m*-semiopen, *m*-preopen, βm -open, *m*-*b*-open) sets in (X, m_X) is denoted by $\alpha m(X)$ (resp. mSO(X), mPO(X), $\beta m(X)$, mBO(X)).

Remark 4. Let (X, m_X) be an *m*-space.

(a) Similar definitions of *m*-semiopen sets, *m*-preopen sets, αm -open sets, βm -open sets are provided in [30].

(b) The families $\alpha m(X)$, mSO(X), mPO(X), $\beta m(X)$ and mBO(X) are all minimal structures on X.

Let (X, m_X) be an *m*-space. Then mSO(X), mPO(X), $\alpha m(X)$, $\beta m(X)$ and mBO(X) are determined by iterating operators mInt and mCl. Hence, they are called *m*-iterate structures and are denoted by mIT(X) (briefly mIT).

Remark 5. (a) It easily follows from Lemma 3.1(3)(4) that mSO(X), mPO(X), $\alpha m(X)$, $\beta m(X)$ and mBO(X) are minimal structures with property \mathcal{B} . They are also shown in Theorem 3.5 of [19], Theorem 3.4 of [22] and Theorem 3.4 of [20] for mSO(X), mPO(X) and $\alpha m(X)$, respectively.

(b) Let (X, m_X) be an *m*-space and mIT(X) an *m*-iterate structure on X. If mIT(X) = mSO(X) (resp. mPO(X), $\alpha m(X)$, $\beta m(X)$), mBO(X)), then we obtain the following definitions (for mSO(X), mPO(X) and $\alpha m(X)$, they are provided in [19], [23] and [20], respectively):

 $mITCl(A) = msCl(A) \text{ (resp. mpCl}(A), \alpha mCl(A), \beta mCl(A), mbCl(A)),$ $mITInt(A) = msInt(A) \text{ (resp. mpInt}(A), \alpha mInt(A), \beta mInt(A), mbInt(A)).$

Remark 6. (1) By Lemmas 1 and 3, we obtain Theorem 3.9 of [19], Theorems 2.3 and 2.4 of [23] and Theorems 3.8 and 3.9 of [20].

(b) By Lemma 2, we obtain Theorem 3.10 of [19], Lemma 3.9 of [22] and Theorem 3.10 of [20].

Definition 11. A function $f : (X, m_X) \to (Y, m_Y)$ is said to be M-semicontinuous [19] (resp. M-precontinuous [22], αM -continuous [20], βM -continuous, M-b-continuous) at $x \in X$ if for each m-open set V containing f(x), there exists m-semiopen set (resp. m-preopen, αm -open, βm -open, *m*-*b*-open) set U of X containing x such that $f(U) \subset V$. The function f is said to be M-semicontinuous (resp. M-precontinuous, αM -continuous, βM -continuous, M-b-continuous) if it has this property at each $x \in X$.

Remark 7. By Definition 11 and Remark 5, it follows that a function $f : (X, m_X) \to (Y, m_Y)$ is *M*-semicontinuous if a function $f : (X, \text{mSO}(X)) \to (Y, m_Y)$ is *M*-continuous.

Definition 12. A function $f : (X, m_X) \to (Y, m_Y)$ is said to be MITcontinuous at $x \in X$ (on X) if $f : (X, mIT(X)) \to (Y, m_Y)$ is M-continuous at $x \in X$ (on X).

Remark 8. Let (X, m_X) be a minimal space. If mIT(X) = mSO(X)(resp. mPO(X), $\alpha m(X)$, $\beta m(X)$, mBO(X)) and $f : (X, m_X) \to (Y, m_Y)$ is *MIT*-continuous, then f is *M*-semicontinuous (resp. *M*-precontinuous, αM -continuous, βM -continuous, *M*-b-continuous).

Since mIT(X) has property \mathcal{B} , by Theorems 1 and 2 and Corollary 1 we have the following theorems.

Theorem 3. For a function $f : (X, m_X) \to (Y, m_Y)$, the following properties are equivalent:

- (a) f is MIT-continuous;
- (b) $f^{-1}(V)$ is mIT-open for every m-open set V of Y;
- (c) $f^{-1}(F)$ is mIT-closed for every m-closed set F of Y;
- (d) mITCl $(f^{-1}(B)) \subset f^{-1}(mCl(B))$ for every subset B of Y;
- (e) $f(mITCl(A)) \subset mCl(f(A))$ for every subset A of X;
- (f) $f^{-1}(\operatorname{mInt}(B)) \subset \operatorname{mITInt}(f^{-1}(B))$ for every subset B of Y.

For a function $f: (X, m_X) \to (Y, m_Y)$, we define $D_{MIT}(f)$ as follows:

 $D_{MIT}(f) = \{x \in X : f \text{ is not } MIT \text{-continuous at } x\}.$

Theorem 4. For a function $f : (X, m_X) \to (Y, m_Y)$, the following properties hold:

$$D_{MIT}(f) = \bigcup_{G \in m_Y} \{ f^{-1}(G) \text{-mITInt}(f^{-1}(G)) \}$$

= $\bigcup_{B \in \mathcal{P}(Y)} \{ f^{-1}(\text{mInt}(B)) \text{-mITInt}(f^{-1}(B)) \}$
= $\bigcup_{B \in \mathcal{P}(Y)} \{ \text{mITCl}(f^{-1}(B)) - f^{-1}(\text{mCl}(B)) \}$
= $\bigcup_{A \in \mathcal{P}(X)} \{ \text{mITCl}(A) - f^{-1}(\text{mCl}(f(A))) \}$
= $\bigcup_{F \in \mathcal{F}} \{ \text{mITCl}(f^{-1}(F)) - f^{-1}(F) \},$

where \mathcal{F} is the family of m-closed sets of (Y, m_Y) .

Remark 9. (a) If mIT(X) = mSO(X) (resp. mPO(X), $\alpha m(X)$, $\beta m(X)$, mBO(X)) and $f : (X, m_X) \to (Y, m_Y)$ is *MIT*-continuous, then by Theo-

rems 3 and 4 we obtain characterizations of M-semicontinuous (resp. M-precontinuous, αM -continuous, βM -continuous, M-b-continuous) functions.

(b) If mIT(X) = mSO(X) (resp. mPO(X), $\alpha m(X)$), then by Theorem 3 we obtain Theorem 3.15 of [19] (resp. Theorem 3.12 of [22], Theorem 3.14 of [20])).

For example, for $mIT(X) = \beta m(X)$ and $m_Y = \beta(Y)$, we obtain the following characterizations.

Corollary 2. For a function $f : (X, m_X) \to (Y, m_Y)$, the following properties are equivalent:

(a) f is βM-continuous;
(b) f⁻¹(V) is βm-open for every β-open set V of Y;
(c) f⁻¹(F) is βm-closed for every β-closed set F of Y;
(d) βmCl(f⁻¹(B)) ⊂ f⁻¹(βCl(B)) for every subset B of Y;
(d) f(βmCl(A)) ⊂ βCl(f(A)) for every subset A of X;
(e) f⁻¹(βInt(B)) ⊂ βmInt(f⁻¹(B)) for every subset B of Y.

5. Some properties of *MIT*-continuous functions

Since the study of MIT-continuity is reduced from the study of M-continuity, the properties of MIT-continuous functions follow from the properties of M-continuous functions in [26].

Definition 13. An *m*-space (X, m_X) is said to be *m*- T_2 [26] if for each distinct points $x, y \in X$, there exist $U, V \in m_X$ containing x and y, respectively, such that $U \cap V = \emptyset$.

Definition 14. An *m*-space (X, m_X) is said to be mIT- T_2 if the *m*-space (X, mIT(X)) is m- T_2 .

Hence, an *m*-space (X, m_X) is $mIT \cdot T_2$ if for each distinct points $x, y \in X$, there exist $U, V \in mIT(X)$ containing x and y, respectively, such that $U \cap V = \emptyset$.

Remark 10. Let (X, m_X) be an *m*-space. If mIT(X) = mSO(X) (resp. mPO(X)), then by Definition 14 we obtain the definition of *m*-semi- T_2 spaces in [21] (resp. *m*-pre- T_2 -spaces in [23]).

Lemma 4 (Popa and Noiri [26]). If $f : (X, m_X) \to (Y, m_Y)$ is an *M*-continuous injection and (Y, m_Y) is m-T₂, then (X, m_X) is m-T₂.

Theorem 5. If $f : (X, m_X) \to (Y, m_Y)$ is an MIT-continuous injection and (Y, m_Y) is m-T₂, then X is mIT-T₂.

Proof. The proof follows from Definition 14 and Lemma 4.

Definition 15. An *m*-space (X, m_X) is said to be *m*-compact [26] if every cover of X by m_X -open sets of X has a finite subcover.

A subset K of an m-space (X, m_X) is said to be m-compact [26] if every cover of K by m_X -open sets of X has a finite subcover.

Definition 16. An *m*-space (X, m_X) is said to be mIT-compact if the *m*-space (X, mIT(X)) is *m*-compact.

A subset K of an m-space (X, m_X) is said to be mIT-compact if every cover of K by mIT-open sets of X has a finite subcover.

Remark 11. Let (X, m_X) be an *m*-space. If mIT(X) = mSO(X) (resp. mPO(X)), then by Definition 16 we obtain the definition of *m*-semicompact spaces in [21] (resp. *m*-precompact spaces in [23]).

Lemma 5 (Popa and Noiri [26]). Let $f : (X, m_X) \to (Y, m_Y)$ be an *M*-continuous function. If K is an *m*-compact set of X, then f(K) is *m*-compact.

Theorem 6. If $f : (X, m_X) \to (Y, m_Y)$ is an MIT-continuous function and K is an mIT-compact set of X, then f(K) is m-compact.

Proof. The proof follows from Definition 16 and Lemma 5.

Definition 17. A function $f : (X, m_X) \to (Y, m_Y)$ is said to have a strongly m-closed graph (resp. m-closed graph) [26] if for each $(x, y) \in$ $(X \times Y) - G(f)$, there exist $U \in m_X$ containing x and $V \in m_Y$ containing y such that $[U \times \mathrm{mCl}(V)] \cap G(f) = \emptyset$ (resp. $[U \times V] \cap G(f) = \emptyset$).

Definition 18. A function $f : (X, m_X) \to (Y, m_Y)$ is said to have a strongly mIT-closed graph (resp. mIT-closed graph) if a function $f : (X, mIT(X)) \to (Y, m_Y)$ has a strongly m-closed graph (resp. m-closed graph).

Hence, a function $f : (X, m_X) \to (Y, m_Y)$ has a strongly mIT-closed graph (resp. mIT-closed graph) if for each $(x, y) \in (X \times Y) - G(f)$, there exist $U \in mIT(X)$ containing x and $V \in m_Y$ containing y such that $[U \times mCl(V)] \cap G(f) = \emptyset$ (resp. $[U \times V] \cap G(f) = \emptyset$).

Lemma 6 (Popa and Noiri [26]). If $f : (X, m_X) \to (Y, m_Y)$ is an *M*-continuous function and (Y, m_Y) is m- T_2 , then f has a strongly m-closed graph.

Theorem 7. If $f : (X, m_X) \to (Y, m_Y)$ is an MIT-continuous function and (Y, m_Y) is m-T₂, then f has a strongly mIT-closed graph.

Proof. The proof follows from Definition 18 and Lemma 6.

Lemma 7 (Popa and Noiri [26]). If $f : (X, m_X) \to (Y, m_Y)$ is a surjective function with a strongly m-closed graph, then (Y, m_Y) is m-T₂.

Theorem 8. If $f : (X, m_X) \to (Y, m_Y)$ is a surjective function with a strongly mIT-closed graph, then (Y, m_Y) is m- T_2 .

Proof. The proof follows from Definition 18 and Lemma 7.

Lemma 8 (Popa and Noiri [26]). Let (X, m_X) be an *m*-space and m_X have property \mathcal{B} . If $f : (X, m_X) \to (Y, m_Y)$ is an injective *M*-continuous function with an *m*-closed graph, then X is *m*-T₂.

Theorem 9. If $f : (X, m_X) \to (Y, m_Y)$ is an injective MIT-continuous function with an mIT-closed graph, then X is mIT-T₂.

Proof. The proof follows from Definition 18, Lemma 8 and the fact that mIT(X) has property \mathcal{B} .

Definition 19. An *m*-space (X, m_X) is said to be *m*-connected [26] if X cannot be written as the union of two nonempty sets of m_X .

Definition 20. An *m*-space (X, m_X) is said to be mIT-connected if the *m*-space (X, mIT(X)) is *m*-connected.

Hence, the *m*-space (X, mIT(X)) is *m*-connected if X cannot be written as the union of two nonempty sets of mIT(X).

Lemma 9 (Popa and Noiri [26]). Let $f : (X, m_X) \to (Y, m_Y)$ be a function, where m_X has property \mathcal{B} . If f is an M-continuous surjection and (X, m_X) is m-connected, then (Y, m_Y) is m-connected.

Theorem 10. If $f : (X, m_X) \to (Y, m_Y)$ is an mIT-continuous surjection and (X, m_X) is mIT-connected, then (Y, m_Y) is m-connected.

Proof. The proof follows from Definition 20, Lemma 9 and the fact that mIT(X) has property \mathcal{B} .

Definition 21. Let (X, m_X) be an m-space and A a subset of X. The m-frontier of A, mFr(A), [27] is defined by mFr(A) = mCl(A) \cap mCl(X \setminus A) = mCl(A) \setminus mInt(A).

Definition 22. Let (X, m_X) be an m-space and A a subset of X. The mIT-frontier of A, mITFr(A), is defined by mITFr(A) = mITCl(A) \cap mITCl(X \ A) = mITCl(A) \ mITInt(A).

Lemma 10 (Popa and Noiri [28]). The set of all points of X at which a function $f : (X, m_X) \to (Y, m_Y)$ is not M-continuous is identical with the union of the m-frontier of the inverse images of m-open sets of (Y, m_Y) containing f(x).

Theorem 11. The set of all points of X at which a function $f : (X, m_X) \rightarrow (Y, m_Y)$ is not MIT-continuous is identical with the union of the mIT-frontier of the inverse images of m-open sets of (Y, m_Y) containing f(x).

Proof. The proof follows from Definition 22 and Lemma 10.

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Received on 11.10.2011 and, in revised form, on 25.07.2012.