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EXTREME COMPACT OPERATORS BETWEEN REAL SPACES OF COMPLEX CONTINUOUS FUNCTIONS

For a compact Hausdorff space X and a homeomorphism $\sigma: X \rightarrow X$, $\sigma \circ \sigma = id$, $C(X, \sigma)$ is a real space of all complex continuous functions on X fulfilling $f(\sigma x) = \overline{f(x)}$. It is shown that a compact operator between two spaces of this kind, which is extreme, is a nice operator.

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1. Introduction

An operator (a compact operator) acting between Banach spaces V and W is called *extreme* if it is an extreme point of the unit ball of the space of bounded (compact bounded) linear operators $L(V, W)$ ($K(V, W)$). The problem of characterizing extreme operators was investigated by several authors (see e.g. [1]). The sufficient condition for an operator to be extreme is that the adjoint operator T^* maps extreme functionals on W into extreme functionals on V . (An operator with this property is called a *nice operator*.) It is natural to ask whether an extreme operator must be nice.

In this paper we will answer this question for $V = C(Y, \tau)$, $W = C(X, \sigma)$ (for definitions see below) and for compact operators only. Since $C(X, \sigma)$ -spaces can be treated as a generalization of $C(X)$ -spaces, we recall now the well-known results (see [2]) about the latter spaces. Let us consider an operator $T: V \rightarrow C(X)$ and let $T^*: X \rightarrow V^*$ be defined by $T^*(x) = \delta_x \circ T$. The association $T \rightarrow T^*$ is an isometric isomorphism

between $L(V, C(X))$ and the space of weak*-continuous functions $C_*(X, V^*)$; the same applies to the spaces $K(V, C(X))$ and the space of norm continuous functions $C(X, V^*)$. Hence, instead of an operator T (bounded or compact) we can consider its representing function (weak*-continuous or norm continuous). T is nice if and only if the representing function takes only extremal values.

In the special case of $V = C(Y)$ the representing function takes values in the space $M(Y)$ of all regular complex Borel measures on Y . The extreme points of the unit ball of $M(Y)$ are the point measures $\alpha \delta_y$, $|\alpha| = 1$, $y \in Y$. So the operator $T: C(Y) \rightarrow C(X)$ is nice if and only if $(Tf)(x) = \alpha(x)(f \circ \phi)(x)$ with $\phi: X \rightarrow Y$ continuous, $\alpha \in C(X)$, $|\alpha(x)| = 1$.

Even in this special case of operator T acting between $C(Y)$ and $C(X)$, the extreme operator need not to be nice. It is, however, true in many cases (one must impose a suitable condition on X , Y or T).

Now, recall that for a compact space X and a homeomorphism $\sigma: X \rightarrow X$ which is also an involution ($\sigma \circ \sigma = id_X$), we define ([6]):

$$C(x, \sigma) = \{f \in C(X) \mid f \circ \sigma = \overline{f}\},$$

where $\overline{f}(x) = \overline{f(x)}$ (complex conjugation). $C(x, \sigma)$ is a real Banach algebra (with a sup norm), and it shares many properties with $C(X)$. In fact, $C(X) \cong C(X \amalg X, \sigma)$, where $X \amalg X$ denotes the disjoint sum and σ is defined in the obvious way. Hence we can treat $C(X, \sigma)$ as a generalization of $C(X)$. This allows us to expect that repetition of the method used for operators $C(Y) \rightarrow C(X)$ will give us results for operators $C(Y, \tau) \rightarrow C(X, \sigma)$. This is really the case, but one difficulty must be overcome: while the mapping $x \mapsto \delta_x$ is a homeomorphism $X \rightarrow C(X)^*$ (weak*-topology), it is not in the case of $C(X, \sigma)^*$ (in general, $\delta_x \notin C(X, \sigma)^*$!). So we will consider the mapping $X \rightarrow L_R(C(X, \sigma), C)$ which maps X into the space of real linear

operators $C(X, \sigma) \rightarrow C$. With the uniform operator norm $L_R(C(X, \sigma), C)$ is a Banach space. The same applies to the space $L_R(V, C)$, where V is any real Banach space.

2. The space $L_R(C(X, \sigma), C)$

Riesz theorem for $C(X, \sigma)$ ([3], Theorem 3.1) states that $C(X, \sigma)^*$ is linearly isometric to the space $M(X, \sigma)$ of all regular complex Borel measures on X fulfilling the condition $\mu = \bar{\mu} \circ \sigma$. If F is a linear real functional on $C(X, \sigma)$ and μ denotes the measure associated with it by Riesz theorem, then

$$F(f) = \int_X f d\mu = \int_X (\Re f) d(\Re \mu) - \int_X (\Im f) d(\Im \mu)$$

for $f \in C(X, \sigma)$, since it is easy to see that $\Im\left(\int_X f d\mu\right) = 0$.

The complexification $M(X, \sigma) + iM(X, \sigma)$ is, as a set, equal to $M(X)$ (for any $\mu \in M(x)$, $\mu = (\mu + \bar{\mu} \circ \sigma)/2 + i(\mu - \bar{\mu} \circ \sigma)/2i$). On the other hand, any $\mu = \mu_1 + i\mu_2 \in M(X, \sigma) + iM(X, \sigma)$ can be considered as an element from $L_R(C(X, \sigma), C)$:

$$\mu(f) = \int_X f d\mu_1 + i \int_X f d\mu_2.$$

The norm in the complexification is given by:

$$\begin{aligned} \|\mu\|_c &= \|\mu_1 + i\mu_2\|_c \\ &= \sup \left\{ (\mu_1(f)^2 + \mu_2(f)^2)^{\frac{1}{2}} \mid f \in B_{C(X, \sigma)} \right\} \\ &= \sup \{ \mu(f) \mid f \in B_{C(X, \sigma)} \}. \end{aligned}$$

Here the supremum has been counted over $B_{C(X, \sigma)}$ and not over $B_{C(X, \sigma)^*}$ since the first set is norming. Note also that μ_1 and μ_2 are complex, but $\mu_1(f)$ and $\mu_2(f)$ are real.

The equality above shows that the norm in the complexification is the usual norm in $L_R(C(X, \sigma), \mathbb{C})$, so we have

Proposition 1. The space $L_R(C(X, \sigma), \mathbb{C})$ is linearly isometric with the complexification $C(X, \sigma)^* + iC(X, \sigma)^*$.

The question arises what relation is between the complexification norm $\|\mu\|_c$ and the usual norm $\|\mu\| = |\mu|(X)$? By the definition we have:

$$\begin{aligned} \|\mu\|_c &= \sup \left\{ \left| \int_X f d(\mu_1 + i\mu_2) \right| : f \in B_{C(X, \sigma)} \right\} \\ &\leq \sup \left\{ \left| \int_X f d(\mu_1 + i\mu_2) \right| : f \in B_{C(X)} \right\} = \|\mu\|. \end{aligned}$$

3. Representing functions

It is well known ([2]) that bounded linear (compact) operators from a Banach space V into the space $C(X)$ are represented by w^* -continuous (norm continuous) mappings from X into V^* . Analogously, the operators from V into $C(X, \sigma)$ will be represented by mappings from X into $L_R(V, \mathbb{C})$. We need, however, the topology in $L_R(V, \mathbb{C})$ which will play the role of w^* -topology in V^* .

Definition 1. ([3]) The ω -topology in $L_R(V, \mathbb{C})$ is the weakest topology such that all the evaluations:

$$\delta_v : L_R(V, \mathbb{C}) \rightarrow \mathbb{C}, \delta_v(v^*) = v^*(v) \quad \text{for } v^* \in L_R(V, \mathbb{C})$$

are continuous.

It is easy to show that the unit ball $B_{L_R(V, \mathbb{C})}$ is ω -compact.

Proposition 2. $\text{ext } B_{L_R(C(X, \sigma), \mathbb{C})} = \{ \alpha \delta_x \mid x \in X, \alpha \in \mathbb{C}, |\alpha| = 1 \}$.

Proof. Suppose that a measure is extreme. We will show that it is a point measure. To this end let \mathcal{B} denote the right-hand side of Proposition 2. We will write simply B instead of $B_{L_R(C(X,\sigma),C)}$. Clearly

$$\overline{\text{conv } F^\omega} \subset B .$$

On the other hand, if $\phi \in \overline{\text{conv } F^\omega}$ then there exists $f \in C(X, \sigma)$, $\|f\| \leq 1$ such that $\phi(f) > 1$. Hence $\phi \notin B$. It follows that

$$B \subset \overline{\text{conv } F^\omega} .$$

Hence ([2], V.8.5) $B \subset F$. Conversely, we will show that for any $x \in X$, $|\alpha| = 1$, $\alpha \delta_x$ is extreme. It is certainly extreme in the unit ball of the space $S_x = \{ \alpha \delta_x \mid \alpha \in C \}$. From the equality:

$$\| \mu \| = \| \mu(\{x\}) \delta_x \| + \| \mu - \mu(\{x\}) \delta_x \| ,$$

(which in fact means that S_x is an L-summand of $M(X)$), it follows that the extreme point of the ball in S_x must also be an extreme point of $M(X)$.

We will need the following theorem and corollary.

Theorem 1. Let V be a real Banach space, (X, σ) a compact Hausdorff space with an involution and let $T:V \rightarrow C(X, \sigma)$ be a linear bounded operator. Then there exists ω -continuous mapping $t: X \rightarrow L_R(V, C)$, $t(\sigma x) = \overline{t(x)}$ such that:

1. $t(x) = \delta_x \circ T$ (i.e., $t(x)(v) = (Tv)(x)$ for $x \in X, v \in V$);
2. $\|T\| = \sup_{x \in X} \|t(x)\|$.

Conversely, if such a map t is given then the operator T defined by (1) is a bounded linear operator from V into $C(X, \sigma)$, with the norm given by (2). The operator T is compact if and only if it is continuous with the norm topology in $L_R(V, C)$.

The proof of this theorem can be found in [3].

Corollary 1. $T \in \text{ext } B_{L(V, C(X, \sigma))}$ ($T \in \text{ext } B_{K(V, C(X, \sigma))}$) if and only if every ω -continuous (norm continuous) map :

$$s: X \rightarrow L_R(V, C)$$

such that $\|t(x) \pm s(x)\| \leq 1$ for each $x \in X$, is identically zero.

Remark. According to Theorem 1, $t(x)$ is an R -linear operator acting from V to C . When $V = C(Y, \tau)$ it can (and will) be treated as a complex measure on Y .

4. Compact operators

Proposition 3. Let $(T \in \text{ext } B_{K(C(Y, \tau), C(X, \sigma))})$. Then for all $x \in X$ the value $t(x)$ of representing function is a point measure of norm one.

Proof. From Theorem 1, $\|t(\cdot)\| = 1$, hence $\|t(x)\| \leq 1$ for all $x \in X$. Let $s(x) = (1 - \|t(x)\|)\phi$, where $\phi \in C(Y, \tau)^*$, $\|\phi\| < 1$. Then $\|t(x) - s(x)\| \leq 1$, hence $s(x) \equiv 0$ by Corollary 1. Therefore $\|t(x)\| \equiv 1$.

Let us now consider the mapping

$$t_v: X \rightarrow M_R(Y), \quad t_v(x) = |t(x)|,$$

where $|t(x)|$ denotes the variation of measure $t(x)$. t_v is continuous with the norm topology in $M_R(Y)$ because

$$\|t_v(x) - t_v(x')\| = \||t(x)| - |t(x')|\| \leq \|t(x) - t(x')\|.$$

Also t_v has probability measures as values. We claim that t_v is extreme in the set:

$$\{f: f \in C(X, M_R(Y)), \text{ all } f(x) \text{ are probability measures}\}.$$

To prove this statement suppose there exists a mapping

$$g: X \rightarrow M_R(Y)$$

which is continuous and such that $t_v(x) \pm g(x) \geq 0$, $(t_v(x) \pm g(x))(Y) = 1$ for all $x \in X$, and $g(\sigma x) = g(x)$. Then $-t_v(x) \leq g(x) \leq t_v(x)$ and it follows that $g(x)$ is absolutely continuous with respect to $t_v(x)$. So, there exists a Borel function h_x with $g(x) = h_x \cdot t_v(x)$. It can be assumed that $-1 \leq h_x(y) \leq 1$ for all $y \in Y$. Let $\mu(x) := h_x \cdot t(x)$. Then $\mu(x) \in L_R(C(Y, \tau), C)$ and:

- a) $x \mapsto \mu(x)$ is continuous (i.e., belongs to $C(X, L_R(C(Y, \tau), C))$),
- b) $\|t(x) \pm \mu(x)\| \leq 1$.

Proof. of a):

$$\begin{aligned} \|\mu(x) - \mu(x')\| &= \|h_x \cdot t(x) - h_{x'} \cdot t(x')\| \\ &\leq \|h_x \cdot t(x) - h_{x'} \cdot t(x')\| + \|h_{x'} \cdot t(x') - h_{x'} \cdot t(x')\| \\ &= \|h_x(t(x) - t(x'))\| + \|(h_x - h_{x'})t(x')\|. \end{aligned}$$

We have ([7] 6.13):

$$\begin{aligned} \|h_x(t(x) - t(x'))\| &= \int_Y |h_x| d|t(x) - t(x')| \leq \\ &\leq \int_Y d|t(x) - t(x')| = \|t(x) - t(x')\| \end{aligned}$$

Also

$$\|(h_x - h_{x'})t(x')\| = \int_Y |h_x - h_{x'}| dt_v(x') = \int_A \dots + \int_{Y \setminus A} \dots,$$

where $A = \{y \in Y : h_x(y) \geq h_{x'}(y)\}$. Then

$$\begin{aligned} \int_A |h_x - h_{x'}| dt_v(x') &= \int_A h_x dt_v(x') - \int_A h_{x'} dt_v(x') \\ &= \int_A h_x dt_v(x) - \int_A h_{x'} dt_v(x) + \int_A h_x d(t_v(x') - t_v(x)) \\ &\leq |g(x) - g(x')|(A) + |t_v(x) - t_v(x')|(A). \end{aligned}$$

For $Y \setminus A$ the analogous inequality holds true, therefore:

$$\|\mu(x) - \mu(x')\| \leq \|t(x) - t(x')\| + |g(x) - g(x')| + \|t(x) - t(x')\|.$$

Hence $x \rightarrow \mu(x)$ is continuous, and that is statement a).

Proof of b):

$$\begin{aligned} \|t(x) \pm \mu(x)\| &= \|(1 \pm h_x)t(x)\| \leq \int_Y |1 \pm h_x| d|t(x)| \\ &= \int_Y (1 \pm h_x) dt(x) = \int_Y dt(x) \pm \int_Y h_x dt_v(x) \\ &= t(x)(Y) \pm g(x)(Y), \end{aligned}$$

and this is equal (by assumption) to 1.

Now, from a), b), and Theorem 1, μ defines the operator M such that $\|T \pm M\| \leq 1$. T is extreme, so $M = 0$ and successively μ , h_x and g are all equal to zero. This proves our claim.

To finish the proof, let us note that $t_v : X \rightarrow M(Y)$ defines an operator $S : C(Y) \rightarrow C(X)$ by the formula:

$$(Sf)(x) = \int_Y f dt_v(x).$$

Since t_v is positive and extreme, S is also positive and extreme. It is known (see e.g. [1]) that S is nice, that is $t_v(x) = S^*(\delta_x)$ is a point measure, and so is $t(x)$. This completes the proof.

Remark. The first four lines of the proof are valid for all bounded (not only compact) operators. Hence

Corollary 2. If $T \in \text{ext } B_{L_R(C(Y, \tau), C(X, \sigma))}$, then the values of its representing function $t(x)$ are of norm one.

From Proposition 2 and Proposition 3 follows:

Theorem 2. Every compact operator T which is extreme in the unit ball in $K(C(Y, \tau), C(X, \sigma))$, is a nice operator.

Proof. If T is extreme then the values of its representing function are point measures of norm one, hence they are extreme $B_{L_R(C(Y, \tau), C(X, \sigma))}$.

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